LISTING OF CLAIMS:

This listing of claims replaces all prior versions and listings of claims in this application:

Claims 1-21 (Canceled).

22. (Currently amended) A method of controlling a position of carriers holding micro-substances comprises the steps of:

pouring remote-acting bodies which can be positionally manipulated by a remote force, micro-substances including a target substance of an assay, and carriers having surfaces with a plurality of holes, cavities, concavities or convexities that are sized to be capable of holding the micro-substances and the remote-acting bodies, into a liquid or a gas or a solid in accordance with a predetermined order,

making the remote-acting bodies and the micro-substances be <u>independently</u> held <u>in the holes, cavities, concavities or convexities</u> in the surfaces of the carrier <u>carriers</u> by <u>simultaneously</u> agitating the <u>suspension system remote-acting bodies, the micro-substances, the carriers and the liquid or gas, and</u>

controlling positions of the carriers holding the micro-substances and the remoteacting bodies in the surfaces thereof by applying a remote force to the remote-acting bodies.

- 23. (Currently amended) A method of controlling positions of carriers holding micro-substances according to claim 22, wherein the remote-acting bodies comprise magnetic particles, the remote force is a magnetic force, and the carriers comprise cellulose.
- 24. (Currently amended) A method of controlling a position of carriers holding micro-substances comprises the steps of:

pouring remote-acting bodies which can be positionally manipulated by a remote force, micro-substances including a target substance of an assay, and carriers <u>having</u> surfaces with a plurality of holes, cavities, concavities or convexities that are sized to be capable of holding the micro-substances and the remote-acting bodies, into a liquid , a gas or a solid in accordance with a predetermined order,

making the remote-acting bodies and the micro-substances be held <u>in the holes</u>, <u>cavities</u>, <u>concavities</u> or <u>convexities</u> in the surfaces of the <u>earrier</u> <u>carriers</u> by agitating the <u>suspension system</u> <u>remote-acting bodies</u>, <u>the micro-substances</u>, <u>the carriers</u>, <u>and the</u> liquid, and

controlling positions of the carriers holding the micro-substances and the remoteacting bodies in the surfaces thereof by applying a remote force to the remote-acting bodies,

the pouring comprising pouring sterilized reductive enzyme into the liquid in addition to the remote-acting bodies, the micro-substances, and the carriers, and comprising selecting the carriers to be sterilized cellulose-carriers, selecting the liquid , gas or solid to be a sterilized liquid culture medium, selecting the remote-acting bodies to be magnetic particles, and selecting the remote force to be a magnetic field.

25. (Currently amended) A method of controlling a position of carriers holding micro-substances comprises the steps of:

pouring remote-acting bodies which can be positionally manipulated by a remote force, micro-substances including a target substance of an assay, and carriers <u>having</u> surfaces with a plurality of holes, cavities, concavities or convexities that are sized to be capable of holding the micro-substances and the remote-acting bodies, into a liquid, liquid or a gas or a solid in accordance with a predetermined order,

making the remote-acting bodies and the micro-substances be <u>independently</u> held <u>in the holes, cavities, concavities or convexities</u> in the surfaces of the carrier carriers by <u>simultaneously</u> agitating the <u>suspension system</u> remote-acting bodies, the <u>micro-substances</u>, the <u>carriers and the liquid or gas</u>,

controlling positions of the carriers holding the micro-substances and the remoteacting bodies in the surfaces thereof by applying a remote force to the remote-acting bodies,

selecting the carriers to be cellulose-carriers having a having therein the plurality of cavities, concavities, convexities or holes, and

selecting the remote-acting bodies to be magnetic particles.

26. (Currently amended) A method of controlling positions of carriers holding micro-substances according to claim 22 25, further comprising the steps of:

selecting the remote-acting bodies to be magnetic bodies,

selecting the remote force to be a magnetic field, and

controlling the magnetic field so as to control the positions of the carriers in a manner which causes filtering of the micro-substances through separation <u>from the liquid or gas</u> of the carriers <u>from the suspension with the remote-acting bodies and micro-substances held thereto</u>.

- 27. (Canceled).
- 28. (Currently amended) A method of controlling positions of carriers holding micro-substances according to claim 22 25 comprising, prior to the pouring, separately preparing the carriers, the remote-acting bodies, and the micro-substances.
- 29. (Currently amended) A method of controlling positions of carriers holding micro-substances according to claim 24, comprising selecting the micro-organisms micro-substances to comprise one of bacteria and viruses.
- 30. (Previously presented) A method of controlling positions of carriers holding micro-substances according to claim 24, comprising selecting the predetermined order to be addition to the liquid culture medium in sequence the sterilized reductive enzyme, the micro-organisms, the sterilized cellulose-carriers, and the magnetic particles.

- 31. (Previously presented) A method of controlling positions of carriers holding micro-substances according to claim 25, comprising selecting the micro-substances to comprise one of antibiotics and anticancer substances.
- 32. (New) A method of controlling positions of carriers holding micro-substances according to claim 24, wherein the agitating includes using a mechanical force.
- 33. (New) A method of controlling positions of carriers holding micro-substances according to claim 26, further comprising:

carrying out the agitating in a manner that includes using a mechanical force; and configuring the carriers so that the holes, cavities, concavities or convexities are large enough to allow the magnetic particles to undergo orientation therein in response to the magnetic field.